

# Mixed boundary element method for eddy current problems

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Research Report No. 2002-16 September 2002

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#### Abstract

We propose a mixed boundary element method for the eddy current problem. It involves two divergence conforming tangent fields on the surface. The zero divergence condition on one of them is enforced with scalar Lagrange multipliers. An LBB Inf-Sup condition is proved for the resulting discrete saddle-point problem, leading to quasi-optimal convergence rates.

### Introduction

The simulation of electromagnetic devices operating at low frequencies is of practical interest to many engineering problems such as the design of electric engines. A basic problem is to determine the total electromagnetic field surrounding a conductor subject to a known electromagnetic excitation. At low frequencies the eddy current model provides a satisfactory approximation of the full Maxwell equations (Ammari, Buffa, Nédélec [1]).

The use of the free-space Green's kernel reduces these equations to integral equations on the surface of the conductor (which might not be connected). Among the many possible choices of integral equations we will use the so-called E-based one. It requires the discretization of divergence-free tangent fields on the surface. Since we are interested in objects with arbitrary topology these are not all rotationals. While Hiptmair [17] uses an explicit (but costly) construction of a supplementary of the space of rotationals in the kernel of the divergence operator, we enforce the constraint on the divergence using Lagrange multipliers. Moreover our proof of stability of the discretization is different from Hiptmair's.

Our analysis is based on the use of discrete Hodge decompositions which for the analysis of integral equations on smooth surfaces was suggested in Christiansen [12]. In most industrial applications the surface is only piecewise smooth, therefore we use also a functional framework proposed by Buffa and Ciarlet [8] and Buffa, Costabel and Sheen [9]. These two techniques have already been successfully combined to study the electric field integral equation both on closed and open surfaces, by Hiptmair and Schwab [18] and Buffa and Christiansen [7]. In addition to these techniques we will use a symmetry argument very similar to the one used in Buffa, Hiptmair, Petersdorff and Schwab [11].

The paper is organized as follows. First we recall the functional setting we will use. Then we provide a quick derivation of the integral equations. Then we turn to their variational formulation, as a saddlepoint problem and show that it is Fredholm. Finally we turn to the Galerkin discretization of this saddlepoint problem and prove the dicrete inf-sup condition under natural hypotheses.

#### 1 Preliminaries

Let  $\Omega_{-}$  be a bounded Lipschitz domain in  $\mathbb{R}^{3}$ . For simplicity we suppose furthermore that  $\Omega_{-}$  is a piecewise flat polyhedron. It models the conductor. We denote by  $\Gamma$  its surface, and by  $\Omega_{+}$  the exterior domain. The unit length outward pointing orthogonal vector field on  $\Gamma$  is denoted by n.

For any  $k \in \mathbb{C}$ , let  $\Phi_k$  denote the single layer potential associated with the operator  $-\Delta + k^2$ . That is, for any field u on  $\Gamma$ ,  $\Phi_k u$  is the field on  $\mathbb{R}^3 \setminus \Gamma$  defined by:

$$(\Phi_k u)(y) = \int_{\Gamma} \frac{e^{-k|x-y|}}{4\pi|x-y|} u(x) \mathrm{d}\mathbf{s}_x. \tag{1}$$

Let  $\gamma$  denote the trace operator on  $\Gamma$ , which is defined on smooth functions

by:

$$\gamma: u \mapsto u|_{\Gamma}.$$
 (2)

On  $\Gamma$ , Sobolev spaces  $H^s(\Gamma)$  can be defined by local charts and dualization, for  $s \in [-1; 1]$ , see e.g. Costabel [16]. One shows that  $\gamma$  has a unique continuous extension to a surjective map:

$$\gamma: H^1(\mathbb{R}^3) \to H^{1/2}(\Gamma). \tag{3}$$

Following Buffa, Ciarlet [8] and Buffa, Costabel and Sheen [9] we recall the functional framework for traces of vector fields. On vector fields we denote by  $\gamma_{\rm T}$  the tagential trace operator:

$$\gamma_{\rm T}: u \mapsto u|_{\Gamma} - (u|_{\Gamma} \cdot n)n.$$
 (4)

We define the space  $L^2_T(\Gamma)$  by:

$$L_{T}^{2}(\Gamma) = \{ u \in L^{2}(\Gamma)^{3} : u \cdot n = 0 \}.$$
 (5)

The operator  $\gamma_T$  has a unique extension to a continuous map  $H^1(\mathbb{R}^3)^3 \to L^2_T(\Gamma)$  and we denote by  $H^{1/2}_T(\Gamma)$  the range of this extension.

When considering traces of fields defined in  $\Omega_{-}$  or  $\Omega_{+}$  we use the notation  $\gamma_{\rm T}^{-}$  and  $\gamma_{\rm T}^{+}$ . We also define  $\gamma_{\times}$ ,  $\gamma_{\times}^{-}$ , and  $\gamma_{\times}^{+}$  by composing  $\gamma_{\rm T}$ ,  $\gamma_{\rm T}^{-}$ , and  $\gamma_{\rm T}^{+}$  with the rotation operator  $(\cdot \times n)$ . Thus we have for smooth fields u:

$$\gamma_{\times} u = u \times n. \tag{6}$$

For s>1 we denote by  $\mathrm{H}^s(\Gamma)$  the subspace of  $\mathrm{H}^1(\Gamma)$  consisting of traces of  $\mathrm{H}^{s+1/2}(\mathbb{R}^3)$ . The gradient operator is defined as a continuous map  $\mathrm{grad}_\Gamma: \mathrm{H}^1(\Gamma) \to \mathrm{L}^2_{\mathrm{T}}(\Gamma)$ . It maps  $\mathrm{H}^{3/2}(\Gamma)$  to  $\mathrm{H}^{1/2}_{\mathrm{T}}(\Gamma)$ , continuously. We denote by  $\mathrm{div}_\Gamma$  the adjoint operator, which is thus continuous  $\mathrm{L}^2_{\mathrm{T}}(\Gamma) \to \mathrm{H}^{-1}(\Gamma)$ , and  $\mathrm{H}^{1/2}_{\mathrm{T}}(\Gamma)' \to \mathrm{H}^{3/2}(\Gamma)'$ .

We denote by X the space:

$$X = \{ u \in H_T^{1/2}(\Gamma)' : \operatorname{div}_{\Gamma} u \in H^{1/2}(\Gamma)' \}.$$
 (7)

We denote by  $\Delta_{\Gamma}$  the Laplace-Beltrami operator defined as the composition  $\operatorname{div}_{\Gamma} \circ \operatorname{grad}_{\Gamma} : \operatorname{H}^{1}(\Gamma) \to \operatorname{H}^{-1}(\Gamma)$ . Let  $P : X \to \operatorname{L}^{2}_{\operatorname{T}}(\Gamma)$  be the map which to any  $u \in X$  associates  $\operatorname{grad}_{\Gamma} p$  where p is a solution of:

$$\Delta_{\Gamma} p = \operatorname{div}_{\Gamma} u. \tag{8}$$

**Proposition 1.1** The map P determines a continuous projector  $X \to X$ . In particular we have a direct sum:

$$X = V \oplus W. \tag{9}$$

where W is kernel of P, which is also the kernel of the divergence operator, and V is the range of P. There is C > 0 such that:

$$\forall u \in V \quad ||u||_X \le C |\operatorname{div} u|_{\mathbf{H}^{-1/2}(\Gamma)} \tag{10}$$

Moreover the injection of V into  $H_T^{1/2}(\Gamma)'$  is compact.

-Proof: The norm estimate follows from the fact that  $\operatorname{div}_{\Gamma}: X \to \operatorname{H}^{-1/2}(\Gamma)$  has closed range, and is injective on V hence determines an isomorphism from V onto its range. The compactness follows from the fact that the injection of  $\operatorname{H}^{1/2}_{\operatorname{T}}(\Gamma)$  into  $\operatorname{L}^2_{\operatorname{T}}(\Gamma)$  is compact.

One shows that  $\gamma_{\times}^{-}$  and  $\gamma_{\times}^{+}$  have unique continuous extensions to maps:

$$H_{\text{curl}}(\Omega_{-}) \to X \quad \text{and} \quad H_{\text{curl}}(\Omega_{+})_{loc} \to X$$
 (11)

respectively, and that these extensions are surjective. Moreover  $\gamma_{\text{\tiny T}}^-$ ,  $\gamma_{\text{\tiny T}}^+$  have unique continuous extensions to maps:

$$H_{\text{curl}}(\Omega_{-}) \to X'$$
 and  $H_{\text{curl}}(\Omega_{+})_{loc} \to X'$  (12)

Moreover the operator  $(\cdot \times n)$  extends to isomorphisms  $X \to X'$  and  $X' \to X$ . We define an operator  $C_k$  on tangent fields on X by:

$$C_k u = (1/2)(\gamma_{\mathrm{T}}^- + \gamma_{\mathrm{T}}^+) \operatorname{curl} \Phi_k u. \tag{13}$$

**Proposition 1.2** The operator  $C_k$  is well-defined and continuous  $X \to X'$ . Moreover:

$$\gamma_{\mathrm{T}}^{\pm} \operatorname{curl} \Phi_k u = \pm u \times n + C_k u, \tag{14}$$

 $C_k - C_0$  is compact  $X \to X'$  and  $C_0$  is symmetric.

-Proof: We first remark that for any  $u \in X$  we have in  $\Omega_- \cup \Omega_+$ :

$$\operatorname{curl}\operatorname{curl}\Phi_k u = (\operatorname{grad}\operatorname{div} - \Delta)\Phi_k u = \operatorname{grad}\Phi_k\operatorname{div}_\Gamma u - k^2\Phi_k u. \tag{15}$$

The continuity of  $C_k$  and compactness of  $C_k - C_0$  then follow straightforwardly from the mapping properties of the singlelayer potential. The trace relations follow from the jump formulas, see e.g. [13] p. 145.

We now turn to the symmetry of  $C_0$ . The proof is a variant of the proof of Theorem 3.9 in [11], which dealt with the case of positive frequencies.

Choose u and v in X. Put:

$$\gamma_{\mathrm{T}}^{-} \operatorname{curl} \Phi_{0} u = a \quad , \quad \gamma_{\mathrm{T}}^{+} \operatorname{curl} \Phi_{0} u = a',$$
 (16)

$$\gamma_{\mathrm{T}}^{-}\operatorname{curl}\Phi_{0}v = b$$
 ,  $\gamma_{\mathrm{T}}^{+}\operatorname{curl}\Phi_{0}v = b'$ . (17)

One checks that for any bilinear form c on X one has:

$$c((a-a'), 1/2(b+b')) + c(1/2(a+a'), (b-b')) = c(a,b) - c(a',b')$$
(18)

We denote by  $\langle \cdot, \cdot \rangle$  the dualities of Sobolev spaces on  $\Gamma$ . We have:

$$\langle C_0 u, v \rangle = \langle 1/2(a+a'), (b-b') \times n \rangle \tag{19}$$

$$= -\langle (a-a'), 1/2(b+b') \times n \rangle + \langle a, b \times n \rangle - \langle a', b' \times n \rangle \quad (20)$$

$$= \langle C_0 v, u \rangle + \langle a, b \times n \rangle - \langle a', b' \times n \rangle. \tag{21}$$

For any R > 0 let  $B_R$  be the ball with radius R and senter 0, let  $S_R$  be the corresponding sphere and let  $n_R$  be the outward normal on  $S_R$ . For any R such that  $\Omega_- \subset B_R$  we can perform the following integrations by parts in  $\Omega_+ \cap B_R$ :

$$-\langle a', b' \times n \rangle$$

$$= \int_{\Omega_{+} \cap B_{R}} \operatorname{curl} \operatorname{curl} \Phi_{0} u \cdot \operatorname{curl} \Phi_{0} v - \operatorname{curl} \Phi_{0} u \cdot \operatorname{curl} \operatorname{curl} \Phi_{0} v$$

$$- \int_{S_{R}} \operatorname{curl} \Phi_{0} u \cdot \operatorname{curl} \Phi_{0} v \times n_{R}$$

$$= \int_{\Omega_{+} \cap B_{R}} \operatorname{grad} \Phi_{0} \operatorname{div}_{\Gamma} u \cdot \operatorname{curl} \Phi_{0} v - \operatorname{curl} \Phi_{0} u \cdot \operatorname{grad} \Phi_{0} \operatorname{div}_{\Gamma} v$$

$$- \int_{S_{R}} \operatorname{curl} \Phi_{0} u \cdot \operatorname{curl} \Phi_{0} v \times n_{R}$$

$$= \langle \gamma_{T}^{+} \operatorname{grad} \Phi_{0} \operatorname{div}_{\Gamma} u, (\gamma_{T}^{+} \Phi_{0} v) \times n \rangle + \langle \gamma_{T}^{+} \Phi_{0} u, (\gamma_{T}^{+} \operatorname{grad} \Phi_{0} \operatorname{div}_{\Gamma} v) \times n \rangle$$

$$- \int_{S_{R}} \operatorname{grad} \Phi_{0} \operatorname{div}_{\Gamma} u, (\Phi_{0} v) \times n_{R} + \Phi_{0} u \cdot (\operatorname{grad} \Phi_{0} \operatorname{div}_{\Gamma} v) \times n_{R}$$

$$- \int_{S_{R}} \operatorname{curl} \Phi_{0} u \cdot \operatorname{curl} \Phi_{0} v \times n_{R}$$

$$(25)$$

The properties of the single layer potential yield:

$$|\Phi_0 u| = O(1/|x|) \tag{26}$$

$$|\operatorname{grad}\Phi_0\operatorname{div}_{\Gamma}u| = O(1/|x|^2) \tag{27}$$

$$|\operatorname{curl} \Phi_0 u| = O(1/|x|^2) \tag{28}$$

Thus we can consider the limit as  $R \to \infty$ :

$$-\langle a', b' \times n \rangle =$$

$$\langle \gamma_{\rm T}^{+} \operatorname{grad} \Phi_{0} \operatorname{div}_{\Gamma} u, (\gamma_{\rm T}^{+} \Phi_{0} v) \times n \rangle + \langle \gamma_{\rm T}^{+} \Phi_{0} u, (\gamma_{\rm T}^{+} \operatorname{grad} \Phi_{0} \operatorname{div}_{\Gamma} v) \times n \rangle$$

$$(29)$$

In the interior domain  $\Omega_{-}$  we apply the same integration by parts formula. Since the orientation of n appears twice, the signs cancel and we obtain:

$$-\langle a, b \times n \rangle =$$

$$\langle \gamma_{\mathsf{T}}^{-} \operatorname{grad} \Phi_{0} \operatorname{div}_{\Gamma} u, (\gamma_{\mathsf{T}}^{-} \Phi_{0} v) \times n \rangle + \langle \gamma_{\mathsf{T}}^{-} \Phi_{0} u, (\gamma_{\mathsf{T}}^{-} \operatorname{grad} \Phi_{0} \operatorname{div}_{\Gamma} v) \times n \rangle$$

$$(30)$$

Noticing that the singlelayer does not jump across  $\Gamma$ , nor the tangential component of its gradient, we obtain:

$$\langle a', b' \times n \rangle = \langle a, b \times n \rangle. \tag{31}$$

This yields the symmetry of  $C_0$ .

We will also use a normal trace operator defined on smooth vector fields by:

$$\gamma_{\rm n}: u \mapsto u|_{\Gamma} \cdot n.$$
 (32)

It has unique continuous extensions to a linear maps  $H_{\mathrm{div}}(\Omega_{\pm}) \to H^{-1/2}(\Gamma)$ .

# 2 E-based boundary integral equation for the eddy current problem

The eddy current problem is to find the electromagnetic field (E, H) solution of:

$$\operatorname{curl} E = -i\mu_r H \quad \text{in} \quad \mathbb{R}^3, \tag{33}$$

$$\operatorname{curl} H = \begin{cases} \tau^2 E & \text{in } \Omega_-, \\ J_s & \text{in } \Omega_+. \end{cases}$$
 (34)

where  $\mu_r = 1$  in  $\Omega_+$ ,  $\tau > 0$  and, for simplicity,  $J_s$  is a divergence-free excitation with compact support in  $\Omega_+$ . Moreover we impose the decay conditions:

$$E(x) = O(1/|x|)$$
 and  $H(x) = O(1/|x|)$ . (35)

Define  $E_s$  by:

$$E_s(x) = -i \int_{\mathbb{R}^3} \frac{J_s(y)}{4\pi |x - y|} dy.$$
(36)

Then the eddy current problem can be reformulated as the following transmission problem for the electric field E:

$$\operatorname{curl}\operatorname{curl}E + i\tau^2\mu_r E = 0 \quad \text{in} \quad \Omega_-, \tag{37}$$

$$\operatorname{curl}\operatorname{curl} U = 0, \operatorname{div} U = 0 \quad \text{in} \quad \Omega_+, \tag{38}$$

$$\gamma_{\mathrm{T}}^{-}E - \gamma_{\mathrm{T}}^{+}U = \gamma_{\mathrm{T}}^{-}E_{s},\tag{39}$$

$$(1/\mu_r)\gamma_{\rm T}^- \operatorname{curl} E - \gamma_{\rm T}^+ \operatorname{curl} U = \gamma_{\rm T}^- \operatorname{curl} E_s, \tag{40}$$

where E is recovered in  $\Omega_+$  as  $E=U+E_s$ . This system of equations is supplied with the decay condition:

$$U/(1+|x|^2)^{1/2} \in L^2(\Omega_+)^3$$
 and  $\operatorname{curl} U \in L^2(\Omega_+)^3$ . (41)

Define  $\kappa$  by:

$$\kappa = (\sqrt{2}/2)(1+i)\tau\sqrt{\mu_r},\tag{42}$$

so that we have:

$$i\tau^2 \mu_r = \kappa^2. \tag{43}$$

In the interior domain  $\Omega_{-}$  we have:

$$\operatorname{curl}\operatorname{curl}E + \kappa^2 E = 0. \tag{44}$$

from which one deduces the following representation formula:

$$E = (1 - 1/\kappa^2 \operatorname{grad} \operatorname{div}) \Phi_{\kappa} \gamma_{\times}^{-} \operatorname{curl} E + \operatorname{curl} \Phi_{\kappa} \gamma_{\times}^{-} E.$$
 (45)

It gives the following two identities:

$$\gamma_{\mathrm{T}}^{-}E = \gamma_{\mathrm{T}}^{-}(1 - 1/\kappa^{2} \operatorname{grad} \operatorname{div})\Phi_{\kappa}\gamma_{\times}^{-}\operatorname{curl} E + 1/2\gamma_{\mathrm{T}}^{-}E + C_{\kappa}\gamma_{\times}^{-}E, \tag{46}$$

$$\gamma_{\rm T}^- \operatorname{curl} E = 1/2\gamma_{\rm T}^- \operatorname{curl} E + C_{\kappa}\gamma_{\times}^- \operatorname{curl} E + \gamma_{\rm T}^- (-\kappa^2 + \operatorname{grad} \operatorname{div}) \Phi_{\kappa}\gamma_{\times}^- E.$$
 (47)

In the exterior domain  $\Omega_+$  we have:

$$\Delta U = 0 \quad \text{and} \quad \text{div } U = 0, \tag{48}$$

which gives the representation formula:

$$U = -\Phi_0 \gamma_{\times}^+ \operatorname{curl} U - \operatorname{grad} \Phi_0 \gamma_{\mathrm{n}}^+ U - \operatorname{curl} \Phi_0 \gamma_{\times}^+ U.$$
 (49)

Since  $\gamma_{\mathbb{T}}^+ \circ \operatorname{grad} = \operatorname{grad}_{\mathbb{T}} \circ \gamma^+$ , it follows that:

$$\gamma_{\rm T}^{+}U = -\gamma_{\rm T}^{+}\Phi_{0}\gamma_{\rm X}^{+}\operatorname{curl}U - \operatorname{grad}_{\Gamma}\gamma^{+}\Phi_{0}\gamma_{\rm n}^{+}U + 1/2\gamma_{\rm T}^{+}U - C_{0}\gamma_{\rm X}^{+}U, \tag{50}$$

and since  $\operatorname{curl}\operatorname{grad}=0$  and  $\Delta=\operatorname{grad}\operatorname{div}-\operatorname{curl}\operatorname{curl}$  we also have:

$$\gamma_{\mathrm{T}}^{+} \operatorname{curl} U = 1/2 \gamma_{\mathrm{T}}^{+} \operatorname{curl} U - C_{0} \gamma_{\times}^{+} \operatorname{curl} U - \gamma_{\mathrm{T}}^{+} \operatorname{grad} \operatorname{div} \Phi_{0} \gamma_{\times}^{+} U.$$
 (51)

Substracting (50) from (46), with the transmission condition (39), and testing against divergence-free  $\mu$  gives:

$$\langle \gamma_{\mathrm{T}}^{-} \Phi_{\kappa} \gamma_{\times}^{-} \operatorname{curl} E + C_{\kappa} \gamma_{\times}^{-} E, \mu \rangle + \langle \gamma_{\mathrm{T}}^{+} \Phi_{0} \gamma_{\times}^{+} \operatorname{curl} U + C_{0} \gamma_{\times}^{+} U, \mu \rangle = \langle (1/2) \gamma_{\mathrm{T}} E_{s}, \mu \rangle.$$
 (52)

Substracting (51) from  $1/\mu_r(47)$  and using with the transmission condition (40) gives:

$$1/\mu_r \left( C_{\kappa} \gamma_{\times}^{-} \operatorname{curl} E + \gamma_{\mathrm{T}}^{-} (-\kappa^2 + \operatorname{grad} \operatorname{div}) \Phi_{\kappa} \gamma_{\times}^{-} E \right) + C_0 \gamma_{\times}^{+} \operatorname{curl} U + \gamma_{\mathrm{T}}^{-} \operatorname{grad} \operatorname{div} \Phi_0 \gamma_{\times}^{+} U = (1/2) \gamma_{\mathrm{T}} \operatorname{curl} E_s.$$
 (53)

We now introduce the quantities:

$$u = \gamma_{\times} E, \qquad (54)$$
  
$$\lambda = 1/\mu_r \gamma_{\times} \operatorname{curl} E. \qquad (55)$$

$$\lambda = 1/\mu_r \gamma_{\times}^{-} \operatorname{curl} E. \tag{55}$$

We remark first that  $\lambda$  is divergence-free. Indeed by (40) we have:

$$\operatorname{div}_{\Gamma} \lambda = \gamma_{\mathrm{n}}^{+} \operatorname{curl} \operatorname{curl} U + \gamma_{\mathrm{n}} \operatorname{curl} \operatorname{curl} E_{s}$$
 (56)

$$= \gamma_{\rm n}(\operatorname{grad}\operatorname{div} - \Delta)E_s = 0. \tag{57}$$

In the above equations (52) and (53) we eliminate  $\gamma_{\times}^{+}U$  and  $\gamma_{\times}^{+}\operatorname{curl} U$  using the transmission conditions (39) and (40). Put into variational form these equations give rise to the system:

$$\begin{cases}
 u \in X \\
 \lambda \in W
\end{cases}
\begin{cases}
 \forall v \in X \\
 \forall \mu \in W
\end{cases}
\begin{cases}
 a(u,v) + c(\lambda,v) = f(v) \\
 c(\mu,u) + b(\lambda,\mu) = g(\mu)
\end{cases}$$
(58)

where the bilinear forms are given on smooth fields by:

$$a(u,v) = -\iint (1/\mu_r) G_{\kappa}(x,y) \left( \operatorname{div}_{\Gamma} u(x) \operatorname{div}_{\Gamma} v(y) + \kappa^2 u(x) \cdot v(y) \right) \operatorname{ds}_x \operatorname{ds}_y$$
$$-\iint G_0(x,y) \operatorname{div}_{\Gamma} u(x) \operatorname{div}_{\Gamma} v(y) \operatorname{ds}_x \operatorname{ds}_y, \tag{59}$$

$$b(\lambda, \mu) = + \iint (\mu_r G_{\kappa}(x, y) + G_0(x, y)) \lambda(x) \mu(y) ds_x ds_y,$$
(60)

$$c(\lambda, v) = \langle (C_{\kappa} + C_0)\lambda, v \rangle, \tag{61}$$

and extended to X and W by continuity.

The right hand sides are given by:

$$f(v) = \langle (-1/2(\cdot \times n) + C_0)\gamma_{\times} \operatorname{curl} E_s, v \rangle - \langle \gamma \Phi_0 \operatorname{div}_{\Gamma} \gamma_{\times} E_s, \operatorname{div}_{\Gamma} v \rangle, (62)$$

$$g(\mu) = \langle (-1/2(\cdot \times n) + C_0)\gamma_{\times} E_s, \mu \rangle - \langle \gamma_{\mathsf{T}} \Phi_0 \gamma_{\times} \operatorname{curl} E_s, \mu \rangle.$$
 (63)

## 3 Fredholm property of the integral equations

Let d be the bilinear form on  $X \times W$  defined by:

$$d((u,\lambda),(v,\mu)) = a(u,v) + c(\lambda,v) + c(\mu,u) + b(\lambda,\mu).$$
(64)

Let  $\Theta$  be the isomorphism  $(u, \lambda) \to (-Pu - 1/\kappa^2(I - P)u, \lambda)$ . The analysis of the system (58) relies on:

**Proposition 3.1** There is a compact bilinear form k on  $X \times W$  such that for a C > 0 it holds:

$$\Re((d+k)((u,\lambda),\overline{\Theta(u,\lambda)}) \ge 1/C\|(u,\lambda)\|_{X\times W}^{2}. \tag{65}$$

-Proof: We denote by s the bilinear form associated with the single layer operator, both on scalar and on vector fields. Thus for scalar fields:

$$s(p,q) = \iint G_{\kappa}(x,y)p(x)q(y)ds_{x}ds_{y}.$$
 (66)

For any  $u \in X$  consider its decomposition  $u = u^V + u^W$  with  $u^V = Pu \in V$  and  $u^W = (I - P)u \in W$ . Associate with it  $v = -\overline{u}^V - 1/\kappa^2\overline{u}^W$ . Then we have:

$$a(u,v) = (1/\mu_r + 1)s(\operatorname{div}_{\Gamma} u^V, \operatorname{div}_{\Gamma} \overline{u}^V) + (1/\mu_r)s(u^W, \overline{u}^W)$$

$$+(\kappa^2/\mu_r)\left(s(u^V, \overline{u}^V) + s(u^V, 1/\kappa^2 \overline{u}^W) + s(u^W, \overline{u}^V)\right).$$
 (68)

It follows from the compactness of the injection  $V \to \mathrm{H}^{1/2}_{\mathrm{T}}(\Gamma)'$  (Proposition 1.1), that all the terms on line (68) are compact. Moreover it follows from the coercivity on  $\mathrm{H}^{-1/2}(\Gamma)$  of the single layer operator that, up to compact bilinear forms, the sum of the terms on line (67) is coercive on X.

Using also  $\mu = \overline{\lambda}$  we have:

$$c(\lambda, v) + c(\mu, u) = c(\lambda, -\overline{u}^V) + c(\overline{\lambda}, u^V) + c(\lambda, -1/\kappa^2 \overline{u}^W) + c(\overline{\lambda}, u^W).$$
 (69)

It follows from the symmetry of  $C_0$  (Proposition 1.2 and the compactness of  $C_{\kappa} - C_0$  that the sum of the first two terms is, up to a compact term, purely imaginary. Moreover the two last terms are compact.

It follows that if d is left injective then it determines an isomorphism  $X \times W \to (X \times W)^*$  and we have the Inf-Sup estimate:

$$\inf_{(u,\lambda) \in X \times W} \sup_{(v,\mu) \in X \times W} \frac{|d((u,\lambda),(v,\mu))|}{\|(u,\lambda)\| \|(v,\mu)\|} > 0, \tag{70}$$

where  $\|\cdot\|$  denotes the standard norm on  $X \times W$ .

Aiming at the discretization of this equation, we remark that it is in general a hard problem to construct explicit subspaces of W, when  $\Gamma$  is allowed to have arbitrary topology. In particular the algorithm proposed by Hiptmair [17] involves an  $N^2$  algorithm to determine surface cycles of trianglulations with N vertices. This is far more than the  $N(\log N)^a$  complexity of multipole matrix-vector products.

We therefore chose to enforce the condition that  $\lambda \in W$  with Lagrange multipliers. Let  $(\Gamma_i)_{i \in I}$  be the family of connected components of  $\Gamma$ . Let Y denote the space:

$$Y = \{ q \in \mathcal{H}^{-1/2}(\Gamma) : \forall i \in I \quad \langle q, 1 \rangle_{\Gamma_i} = 0 \}.$$
 (71)

Notice first that  $Y = \operatorname{div}_{\Gamma} X$  and that if  $q \in Y$ , if  $u \in V$  is the solution of  $\operatorname{div}_{\Gamma} u = q$  then by Proposition 1.1 we have an estimate of the form  $||u||_X \leq C||q||_Y$ .

Next let  $s_0$  be the bilinear form obtained by substituting 0 for  $\kappa$  in s. We define a form e by:

$$e((u,\lambda),q) = s_0(\operatorname{div}_{\Gamma}\lambda,q).$$
 (72)

By the coercivity of  $s_0$  on  $H^{-1/2}(\Gamma)$  it follows that we have the Babuska-Brezzi compatibility estimate:

$$\inf_{q \in Y} \sup_{(u,\lambda) \in X \times X} \frac{|e((u,\lambda),q)|}{\|(u,\lambda)\| \|q\|} > 0.$$
 (73)

We extend d from a bilinear form on  $X \times W$  to one on  $X \times X$  by keeping the expressions (59), (60) and (61) in the definition (64) of d. The original problem (58) is equivalent to one of the form: find  $(u, \lambda) \in X \times X$  and  $q \in Y$ , such that:

$$\begin{cases} \forall (v,\mu) \in X \times X & d((u,\lambda),(v,\mu)) + e((v,\mu),q) = l((v,\mu)) \\ \forall p \in Y & e((u,\lambda),p) = 0 \end{cases}$$
 (74)

Here  $l((v,\mu)) = f(v) + \tilde{g}(\mu)$  where  $\tilde{g}$  is any continuous extension of g from W to X. By the above Inf-Sup conditions it follows from Nicolaides' [22] theorem that this problem is uniquely solvable when d is left injective.

Notice that for our purposes, in (72),  $s_0$  can be replaced by any bilinear form which is coercive on  $H^{-1/2}(\Gamma)$ .

### 4 Discrete Inf-Sup condition

Suppose we have Galerkin spaces  $X_h \subset X$  and  $Y_h \subset Y$ . Then we consider the problem of finding  $(u, \lambda) \in X_h \times X_h$  and  $q \in Y_h$ , such that:

$$\begin{cases} \forall (v,\mu) \in X_h \times X_h & d((u,\lambda),(v,\mu)) + e((v,\mu),q) = l((v,\mu)) \\ \forall p \in Y_h & e((u,\lambda),p) = 0 \end{cases}$$
(75)

In general this problem does not satisfy discrete uniform Inf-Sup conditions. Therefore we shall make some additional assumptions on  $X_h$  and  $Y_h$ . First we suppose that:

$$Y_h = \operatorname{div}_{\Gamma} X_h = \{ \operatorname{div}_{\Gamma} u : u \in X_h \}. \tag{76}$$

Furthermore we define:

$$W_h = \{ u \in X_h : \operatorname{div}_{\Gamma} u = 0 \} \tag{77}$$

and:

$$V_h = \{ u \in X_h : \forall w \in W_h \quad \int u \cdot w = 0 \}.$$
 (78)

Then we have:

$$X_h = V_h \oplus W_h, \tag{79}$$

but in general  $V_h$  is not a subspace of V.

Recall that for any two closed subspaces  $X_0$  and  $X_1$  of X the gap  $\delta(X_0, X_1)$  is defined by:

$$\delta(X_0, X_1) = \sup_{u_0 \in X_0} \inf_{u_1 \in X_1} \|u_0 - u_1\| / \|u_0\|.$$
 (80)

We say that the family  $(X_h)$  of spaces is approximating if:

$$\forall u \in X \quad \lim_{h \to 0} \inf_{u_h \in X_h} ||u - u_h|| = 0.$$
 (81)

**Theorem 4.1** If d is left injective,  $(X_h)$  is approximating and  $\delta(V_h, V) \to 0$  then the system (75) satisfies uniform discrete Inf-Sup conditions for small enough h.

–Proof: (i) Compatibility condition: Let P be the projector onto V parallel to W. Then we have:

$$\forall u_h \in V_h \quad \|u_h\| \leq \|u_h - Pu_h\|_X + \|Pu_h\| \tag{82}$$

$$\leq \|I - P\|\delta(V_h, V)\|u_h\| + \|\operatorname{div}_{\Gamma} u_h\|_{Y}.$$
 (83)

Therefore we have an estimate of the form there is  $h_0 > 0$  and C > 0 such that for all  $h < h_0$ :

$$\forall u_h \in V_h \quad \|u_h\|_X \le C \|\operatorname{div}_{\Gamma} u_h\|_Y. \tag{84}$$

Then, given  $q \in Y$ , if  $u_h \in V_h$  is the solution of  $\operatorname{div}_{\Gamma} u_h = q$  we have:

$$e((0, \overline{u}_h), q) / \|u_h\|_X = s_0(\operatorname{div}_{\Gamma} \overline{u}_h, q) \ge 1 / C \|q\|.$$
 (85)

(ii) Inf-Sup condition on the kernel. Remark that for all  $(u, \lambda) \in X_h \times X_h$  if:

$$\forall q \in Y_h \quad e((u,\lambda), q) = 0, \tag{86}$$

then  $\operatorname{div}_{\Gamma} \lambda = 0$ , hence:

$$\forall q \in Y \quad e((u,\lambda),q) = 0. \tag{87}$$

In other words the left kernel of e on  $(X_h \times X_h) \times Y_h$  is  $X_h \times W_h$  which is a subspace of  $X \times W$ . Unfortunately this subspace is not stable under  $\Theta$ . Let  $\Theta_h$  denote the map:

$$\Theta_h(u_h, \lambda_h) \mapsto (-u_h^{V_h} - 1/\kappa^2 u_h^{W_h}, \lambda_h), \tag{88}$$

where  $u_h$  is decomposed as  $u_h = u_h^{V_h} + u_h^{W_h}$  with  $(u_h^{V_h}, u_h^{W_h}) \in V_h \times W_h$ . By Lemma 6.1 part (ii), putting  $\delta_h = \delta(V_h, V)$  we have an estimate of the form:

$$\|\Theta_h(u_h, \lambda_h) - \Theta(u_h, \lambda_h)\| \le C\delta_h \|(u_h, \lambda_h)\|. \tag{89}$$

Using equation (65) it follows that for small enough h we have an estimate of the form:

$$\mathfrak{Re}(d+k)((u_h,\lambda_h),\overline{\Theta_h(u_h,\lambda_h)}) \ge 1/C\|(u_h,\lambda_h)\|_{X\times X}^2,\tag{90}$$

from which we can deduce the discrete Inf-Sup condition: There is  $h_0 > 0$  and C > 0 such that for all  $h < h_0$ :

$$\inf_{(u_h,\lambda_h)\in X_h\times W_h} \sup_{(v_h,\mu_h)\in X_h\times W_h} \frac{|(d+k)((u_h,\lambda_h),(v_h,\mu_h))|}{\|(u_h,\lambda_h)\|\|(v_h,\mu_h)\|} \ge 1/C.$$
(91)

By virtue of the general theorems on injective compact pertubations of bilinear forms, a similar estimate holds with (d+k) replaced by d when  $(X_h)$  is approximating, which is our claimed result.

Examples of Galerkin spaces for which the condition  $\delta(V_h,V) \to 0$  holds include the case when we have triangulations  $\mathcal{T}_h$  on  $\Gamma$  upon which we consider Raviart-Thomas finite elements for  $X_h$  and piecewise polynomials of degree one less and with zero integral on each  $\Gamma_i$  (this condition can be enforced with one Lagrange multiplier per connected component of  $\Gamma$ ) for  $Y_h$ . This was proved in Hiptmair-Schwab [18]. A detailed proof can also be found in Christiansen [13]. Thus for lowest order finite elements we have two degrees of freedom per edge and one per face of the triangulation.

As is well-known the Inf-Sup condition implies quasi-optimal convergence of the Galerkin solution  $(u_h, \lambda_h)$  towards the continuous solution  $(u, \lambda)$ , i.e:

$$\|(u,\lambda) - (u_h,\lambda_h)\|_{X\times X} \le C \inf_{(u',\lambda')\in X_h\times X_h} \|(u,\lambda) - (u',\lambda')\|_{X\times X}.$$
 (92)

### 5 Extension to curved boundaries

In many applications the scatterer is not piecewise flat, but only piecewise smooth. In this case parametric Finite Elements should be used, and it is our goal to define them here.

Suppose we have a triangulation  $\mathcal{T}_h$  of  $\Gamma$ . We denote by  $\Gamma_h^1$  the affine polyhedron it determines. We equip each triangle  $T \in \mathcal{T}_h$  with the set  $\Sigma_T^p$  of points with barycentric coordinates which are multiples of 1/p. Put  $\Sigma_h^p = \bigcup_{T \in \mathcal{T}_h} \Sigma_T^p$ . We suppose we are given a map  $F_h^p : \Sigma^p \to \Gamma$ . We extend  $F_h^p$  to a function  $\overline{F}_h^p : \Gamma_h^1 \to \mathbb{R}^3$  by enforcing that on each  $T \in \mathcal{T}_h$  its restriction is the  $P^p$  function coinciding with  $F_h^p$  on  $\Sigma_T^p$ . Then the  $P^p$ -approximation of  $\Gamma$  is defined as the range of  $\overline{F}_h^p$  and denoted  $\Gamma_h^p$ . In the following  $\overline{F}_h^p$  is denoted  $F_h^p$ .

the range of  $\overline{F}_h^p$  and denoted  $\Gamma_h^p$ . In the following  $\overline{F}_h^p$  is denoted  $F_h^p$ .

By way of  $F_h^p$  standard finite element spaces on  $\Gamma_h^1$  can be transported to  $\Gamma_h^p$ .

The problem is now to define a transport function  $G_h^p$  from  $\Gamma_h^p$  to  $\Gamma$ . When  $\Gamma$  is globally smooth the orthogonal projection was used in Nédélec [20]. We extend the technique to piecewise smooth boundaries by a method used in Lenoir [19] to define parametric volume finite elements in smooth domains.

We suppose  $\Gamma$  can be decomposed as:

$$\Gamma = \bigcup_{i \in I_2} \gamma_i^2 \ \bigcup_{i \in I_1} \gamma_i^1 \ \bigcup_{i \in I_0} \gamma_i^0. \tag{93}$$

such that the sets  $\gamma_i^j$  are pairwise disjoint and such that for each  $i,j,\,\gamma_i^j$  is a smooth j-dimensional manifold.

We suppose the triangulation  $\mathcal{T}_h$  is maid up of triangulations for the patches  $\gamma_i^2$  which coincide along the edges  $\gamma_j^1$  and cointain the vertices  $\gamma_k^0$ . A more precise definition would require the theory of simplicial complexes.

We now construct  $G_h^p$  for a patch  $\gamma_i^2$ . Let T be a triangle of  $\mathcal{T}_h$ . If T contains at most one point of  $\partial \gamma_i^2$  then  $G_h^p$  is the orthogonal projection, which is well defined. If T contains two points on  $\partial \gamma_i^2$ , say  $P_0$  and  $P_1$  belonging to a set  $\overline{\gamma_j^1}$  we let the third point be  $P_3$  and denote  $\lambda_0, \lambda_1, \lambda_2$  the barycentric coordinates in T. The orthogonal projection onto  $\overline{\gamma_j^1}$  induces a bicontinuous bijection  $P_j^1$  from the edge  $[P_0, P_1]$  to its range in  $\overline{\gamma_j^1}$ . We let  $G_h^p(P)$  be the orthogonal projection onto  $\overline{\gamma_i^2}$  of the point:

$$(\lambda_0 + \lambda_1) P_i^1 (1/(\lambda_0 + \lambda_1)(\lambda_0 P_0 + \lambda_1 P_1)) + \lambda_2 P_2. \tag{94}$$

The other possibilities (in particular three points on the boundary) we rule out. On two neighbouring triangles the definitions coincide, leading to a globally defined map  $G_h^p:\Gamma_h^p\to\Gamma$ . The triangulations are constructed such that this map is a bicontinuous bijection.

Let  $\Xi_h^p$  be the inverse of  $G_h^p \circ F_h^p$ . The Raviart-Thomas vector fields on  $\Gamma_h^1$  are the transported to  $\Gamma$  by  $G_h^p \circ F_h^p$  using Piola's transform:

$$u \mapsto \operatorname{Jac} \Xi_h^p \mathrm{D}^{-1} \Xi_h^p u \circ \Xi_h^p.$$
 (95)

Piece-wise polynomials on  $\Gamma_h^1$  are transported to  $\Gamma$  according to:

$$u \mapsto \operatorname{Jac} \Xi_h^p u \circ \Xi_h^p.$$
 (96)

The transport formulas were chosen in order to satisfy the property:

$$\operatorname{div}_{\Gamma} \operatorname{Jac} \Xi_{h}^{p} \operatorname{D}^{-1} \Xi_{h}^{p} u \circ \Xi_{h}^{p} = \operatorname{Jac} \Xi_{h}^{p} \operatorname{div}_{\Gamma_{h}^{1}} u \circ \Xi_{h}^{p}. \tag{97}$$

With this property the analysis of the preceding sections carry over to the case of curved boundaries.

# 6 Appendix

**Lemma 6.1** Let X be a Banach space and  $X = V \oplus W$  be a splitting of X into a direct sum of closed subspaces. Suppose  $(X_h)$  is a family of closed subspaces that can be split into direct sums of closed subspaces  $X_h = V_h \oplus W_h$  such that  $\delta_h = \max\{\delta(V_h, V), \delta(W_h, W)\} \to 0$ .

(i) Then there is  $h_0 > 0$  and C > 0 such that for all  $h < h_0$  and  $(v_h, w_h) \in V_h \times W_h$ :

$$||v_h|| + ||w_h|| \le C||v_h + w_h||. \tag{98}$$

(ii) Moreover there is  $h_0 > 0$  and C > 0 such that for all  $h < h_0$  and  $u_h \in X_h$ , if  $(v_h, w_h)$  is its decomposition in  $V_h \times W_h$  and (v, w) is the one in  $V \times W$  then:

$$||v - v_h|| + ||w - w_h|| \le C\delta_h ||u_h||.$$
(99)

-Proof: (i) Let P denote the projection with range V and kernel W. For any  $(v_h, w_h) \in V_h \times W_h$ , with  $u_h = v_h + w_h$  we have:

$$||v_h|| \le ||P(v_h + w_h)|| + ||Pw_h|| + ||Pv_h - v_h|| \tag{100}$$

$$\leq ||P|| ||u_h|| + ||P||\delta_h||w_h|| + ||I - P||\delta_h||v_h||. \tag{101}$$

Similarly:

$$||w_h|| \le ||I - P|| \, ||u_h|| + ||I - P||\delta_h||v_h|| + ||P||\delta_h||w_h|| \tag{102}$$

Putting  $M = \max\{\|P\|, \|I - P\|\}$ , adding and rearranging we have:

$$||v_h|| + ||w_h|| \le 2M/(1 - \delta_h 2M)^{-1} ||u||_h.$$
(103)

This proves the first part of the lemma.

(ii) With the above notations we have:

$$||Pu_h - v_h|| \le ||Pv_h - v_h|| + ||Pw_h|| \tag{104}$$

$$\leq M\delta_h \|v_h\| + M\delta_h \|w_h\|. \tag{105}$$

Similarly we have:

$$||(I - P)u_h - w_h|| \le M\delta_h ||w_h|| + M\delta_h ||v_h||.$$
(106)

Together with the first estimate this gives the second part of the lemma.  $\Box$ 

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